

# REMARKS ON A PROBLEM IN SYMMETRIC FUNCTIONS

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Received April 4, 1955

## 1. INTRODUCTION

IN a former paper (*Proc. Ind. Acad. Sci.*, 1952, 35 A, referred to hereafter as **p**) we considered the following problem: Given that the set of variables  $(x_1, x_2, \dots, x_n)$  satisfies the conditions:

$$(a) 0 \leq x_1 \leq x_2 \leq \dots \leq x_n$$

$$(b) \Sigma x_1 = k_1$$

$$\Sigma x_1 x_2 = k_2$$

.....

$$\Sigma x_1 \dots x_{n-1} = k_{n-1}$$

where  $k_1, k_2, \dots, k_{n-1}$  are fixed but unspecified constants.

(c) Maximum and minimum values of the successive  $x$ 's occur alternately, *i.e.*, if  $x_1$  has its maximum value,  $x_2$  has its minimum value,  $x_3$  its maximum value and so on.

To find, under these conditions,  $n$  numbers  $(a_1, a_2, \dots, a_n)$  such that

$$0 \leq x_1 \leq a_1 \leq x_2 \leq a_2 \leq \dots \leq a_{n-1} \leq x_n \leq a_n.$$

It was shown in **p** that the  $a$ 's are the roots of certain Tschebyscheff polynomials and that they possess certain symmetry properties.

The object of the present note is to offer some supplementary remarks indicating an alternative formulation of the problem as a problem of conditional maxima and minima. This formulation shows that the original problem



has a pair of equal roots, the condition for which is the vanishing of the eliminant of

$$f(x) \equiv x^n - k_1 x^{n-1} + \dots \mp k_{n-1} x \pm k_n = 0$$

$$f'(x) \equiv nx^{n-1} - (n-1)k_1 x^{n-2} + \dots \mp k_{n-1} = 0$$

By Sylvester's theorem, the eliminant will be a relation of the form

$$F(k_1, k_2, \dots, k_{n-1}, k_n) = 0 \tag{5}$$

in which  $k_1, k_2, \dots, k_{n-1}$  each occur to the degree  $n$  but  $k_n$  (or  $\phi$ ) occurs to the degree  $n-1$ , corresponding to the  $n-1$  stationary values. These  $(n-1)$  stationary values will in general be different, but by a proper choice of  $k_1, k_2, \dots, k_{n-1}$ , the eliminant (5) can be reduced to the form

$$(\phi - \lambda)^r (\phi - \mu)^s = 0, \quad r + s = n - 1 \tag{6}$$

Conversely, if (5) reduces to the form (6), the  $k$ 's are determined. The two stationary values given by (6) correspond to the 'two extreme solutions' referred to above. This offers a natural approach to our original problem but it seems difficult to carry out this programme in general.

### 3. OTHER RELATED PROBLEMS

The conditions for an extremum in the problem considered above can also be written as follows:—

$$\left. \begin{aligned} d(\Sigma x_1) &= 0 \\ d(\Sigma x_1 x_2) &= 0 \\ \dots\dots\dots & \\ d(\Sigma x_1 x_2 \dots x_{n-1}) &= 0 \\ d(x_1 \dots x_n) &= 0 \end{aligned} \right\} \tag{7}$$

the last of which holds because of the required stationary character of the function, while the remaining equations are consequences of the constancy of the concerned functions. It will be observed that *exactly the same equations are obtained if, instead of making  $\phi = k_n$  stationary, any one of the other  $k$ 's is made an extremum, all the remaining  $k$ 's being fixed.* Thus the condition (3) for an extremum holds for all the  $n$  different problems:—

(i) any one  $k_r = \text{extremum}$ ,  $r = 1, 2, \dots$  or  $n$

(ii) all other  $k_s$ ,  $(n-1)$  in number,  $(s \neq r)$  fixed.

As in the original problem, we consider for each of the new problems only the case corresponding to the maximum number of double roots. By way of illustration we give the solutions for  $n = 3$  and  $n = 4$ .

The Case  $n = 3$ 

Problem	$a_0$	$a_1$	$a_2$	$a_3$
$k_1 = \text{Stationary}$ $k_2, k_3$ fixed	$\frac{m+1}{2m}$	1	$m$	$\frac{m(m+1)}{2}$
$k_2 = \text{Stationary}$ $k_3, k_1$ fixed	$\frac{2}{m+1}$	1	$m$	$\frac{2m^2}{m+1}$
$k_3 = \text{Stationary}$ $k_1, k_2$ fixed	$\frac{3-m}{2}$	1	$m$	$\frac{3m-1}{2}$

The Case  $n = 4$ 

Problem	$a_0$	$a_1$	$a_2$	$a_3$	$a_4$
$k_1 = \text{Stationary}$ $k_2, k_3$ and $k_4$ fixed	$\frac{m^2(m-1)}{(m+1)(m-2)^2}$	1	$m^2-1$	$\frac{m^2(m^2-1)}{4-m^2}$	$\frac{m^2(m+1)}{(m-1)(m+2)^2}$
$k_2 = \text{Stationary}$ $k_3, k_4$ and $k_1$ fixed	$\frac{(m^2-m+1)-}{(m+1)\sqrt{m^2+1}}$	1	$m$	$m^2$	$\frac{(m^2-m+1)+}{(m+1)\sqrt{m^2+1}}$
$k_3 = \text{Stationary}$ $k_4, k_1$ and $k_2$ fixed	$a$	1	$m$	$\frac{m(3m-1)}{m+1}$	$c$
	where $a, c$ are the roots of $(m+1)^2 t^2 - 2(2m+1)(m^2-1)t + (3m-1)^2 = 0$				
$k_4 = \text{Stationary}$ $k_1, k_2$ and $k_3$ fixed	$m - (m-1)\sqrt{2}$	1	$m$	$2m-1$	$m + (m-1)\sqrt{2}$

In our original problem ( $k_n$ -stationary) we took  $a_0 = 0$ . It is readily verified that the Polynomial Identity formulated for the case  $a_0 \neq 0$  transforms itself into the very identity for the case  $a_0 = 0$  (p, p. 217, 220) by the mere substitution:

$$\gamma v = t - a_0$$

$$a_r - a_0 = a_r'$$

$$\xi - a_0 = \gamma \xi'$$

$$\gamma \neq 0$$

Taking  $\gamma = 1$ , we see that, when  $a_0 \neq 0$ , the differences  $(a_0 - a_1), (a_2 - a_0) \dots, (a_n - a_0)$  are the roots of the Tschebyscheff polynomial found in **p**. We might here draw attention to one important distinction between the problem of  $k_n$  stationary and the others corresponding to  $k_r$  ( $r \neq n$ ) stationary. In the former case, the ratios  $(a_1 - a_0) : (a_2 - a_0) : \dots : (a_n - a_0)$  are independent of any arbitrary parameter; this is *not* the case for the other problems.

#### 4. REMARKS ON THE SYMMETRY PROPERTY

For the solution of the original problem we established in **p** the following symmetry relations for any  $n$ :

$$a_0 + a_n = a_1 + a_{n-1} = a_2 + a_{n-2} = \dots \tag{8}$$

It should be possible to prove these relations from the basic governing relations, without obtaining the explicit form of the solution.

Consider the case  $n = 2m + 1$ . We have then the polynomial identity (**p**, p. 217), *generalised* to the present case  $a_0 \neq 0$ ,

$$\begin{aligned} \phi(t) &\equiv (t - a_0) (t - a_2)^2 (t - a_4)^2 \dots (t - a_{2m})^2 \\ &\equiv (t - a_1)^2 (t - a_3)^2 \dots (t - a_{2m-1})^2 (t - \xi) + \\ &\quad (\xi - a_0) (a_1 - a_0)^2 (a_3 - a_0)^2 \dots (a_{2m-1} - a_0)^2. \end{aligned}$$

Since this is an identity,  $a_0, a_2, a_4, \dots, a_{2m}$  as zeros of  $\phi(t)$  are *uniquely* determined as functions of  $a_1, a_3, \dots, a_{2m-1}, \xi$ . By writing  $\xi - t + a_0$  for  $t$ , the identity becomes, after a slight rearrangement

$$\begin{aligned} (t - a_0) [t - (\xi + a_0 - a_1)]^2 [t - (\xi + a_0 - a_3)]^2 \\ [t - (\xi + a_0 - a_{2m-1})]^2 \\ = [t - (\xi + a_0 - a_2)]^2 [t - (\xi + a_0 - a_4)]^2 \\ [t - (\xi + a_1 - a_{2m})]^2 (t - \xi) \\ + (\xi - a_0) (a_1 - a_0)^2 (a_3 - a_0)^2 \dots (a_{2m-1} - a_0)^2 \end{aligned}$$

Comparing this with the previous form we can see that the identity is satisfied if we write

$$\xi + a_0 - a_1 = a_{2m}$$

$$\xi + a_0 - a_3 = a_{2m-2}$$

.....

$$\xi + a_0 - a_{2m-1} = a_2$$

Of course,  $\xi = a_{2m+1} = a_n$ .

On account of the above-mentioned uniqueness, it follows that the sought relations between  $(a_0, a_2, a_4, \dots, a_{2m})$  and  $(a_1, a_3, \dots, a_{2m-1}, \xi)$  are just these, which are of course the desired symmetry relations. However a similar proof does not work for the case  $n = 2m$ .