## A THEOREM OF CRAMÉR AND WOLD REVISITED

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ABSTRACT. Let  $H = \{(x, y); x > 0\} \subseteq \mathbb{R}^2$  and let *E* be a Borel subset of *H* of positive Lebesgue measure. We prove that if  $\mu$  and v are two probability measures on  $\mathbb{R}^2$  such that  $\mu(\sigma(E)) = v(\sigma(E))$  for all rigid motions  $\sigma$  of  $\mathbb{R}^2$ , then  $\mu = v$  This generalizes a well-known theorem of Cramér and Wold.

1. Introduction. A celebrated theorem of H. Cramér and H. Wold particularly well known to probabilists (see [3]) asserts: If  $\mu$  and v are probability measures on  $\mathbb{R}^2$ such that they agree on all half planes, then  $\mu = v$ . This can be reformulated in the following way: Let  $H = \{(x, y) \in \mathbb{R}^2; x \ge 0\}$ . If  $\mu$  and v are probability measures such that  $\mu(\sigma(H)) = v(\sigma(H))$  for all rigid motions  $\sigma$  of  $\mathbb{R}^2$ , then  $\mu = v$ . The aim of this note is to generalize this result to an arbitrary Borel set E of positive Lebesgue measure contained in H. The results in this paper are valid for  $\mathbb{R}^n$ ,  $n \ge 2$ , but for notational simplicity we consider  $\mathbb{R}^2$ —the same proofs go through for any  $n \ge 2$ . A special case of our result—for a restricted class of Borel sets E, i.e. those that "pave" the half space H—appears in [4, §I.2.4]. However, the methods in [4] are different, where the Radon transform is used.

2. Notation and terminology. For any unexplained notation or terminology please see [5].

By a rigid motion of  $\mathbf{R}^2$  we mean a homeomorphism of  $\mathbf{R}^2$  of the form  $(x, y) \rightarrow T(x, y) + (x_0, y_0)$ , where  $(x_0, y_0)$  is a fixed vector in  $\mathbf{R}^2$  and T is a special orthogonal linear transformation of  $\mathbf{R}^2$  (i.e. T is a matrix of the form

$$\begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \Big).$$

Throughout this paper  $\lambda$  denotes the Lebesgue measure on  $\mathbb{R}^2$ . Let C denote the class of all (finite) complex measures on  $\mathbb{R}^2$ . If T is a tempered distribution (in the sense of Schwartz), then  $\hat{T}$  denotes the Fourier transform of T (which is again a distribution) and Supp T denotes the (closed) support of T. For standard facts regarding distributions, Fourier transforms etc., see [5]. If g is a bounded Borel function on  $\mathbb{R}^2$ , then g defines a tempered distribution and  $\hat{g}$  will denote the (distributional) Fourier transform of g. If  $\mu$  is a finite complex measure, then  $\mu * g$  is the bounded Borel function defined by

$$(\mu * g)(x) = \int_{\mathbf{R}^2} g(x - y) d\mu(y).$$

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Finally we note that for a complex measure or an  $L^1$ -function the usual notion of Fourier transform coincides with the notion of distributional Fourier transform.

If  $E \subset \mathbb{R}^2$ , let  $1_E$  denote the indicator function of E, i.e.  $1_E(x) = 1$  if  $x \in E$  and  $1_E(x) = 0$  if  $x \notin E$ .

*H* will always stand for the subset of  $\mathbb{R}^2$  defined by  $H = \{(x, y) \in \mathbb{R}^2; x \ge 0\}$ .

We end this section by quoting a result that will be needed in the next section.

**PROPOSITION.** Let f be a bounded measurable function on  $\mathbb{R}^2$  and  $\mu \in C$ . If  $\mu * f$  vanishes identically, then  $\hat{\mu}$  vanishes on Supp  $\hat{f}$ .

(*Note*. For a proof of this theorem, we refer to p. 232 of [2]. In [2]  $\mu$  is taken to be an  $L^1$ -function but by convolving  $\mu$  with an  $L^1$ -function whose Fourier transform is nowhere vanishing (e.g. the Gaussian) we can get the theorem quoted above. Note also that Supp  $\hat{f}$  is called "spectrum of f" in [2].)

3. The main result. We start with a proposition which combined with the proposition quoted in §2 yields the main result.

PROPOSITION 3.1. Let h be a nonnegative bounded Borel measurable function on  $\mathbb{R}^2$  such that h is positive on a set of positive Lebesgue measure and such that Supp  $h \subset H$ . Then  $\mathbb{R} \times \{0\} \subset \text{Supp } \hat{h}$ .

PROOF. First assume  $h \in L^1(\mathbb{R}^2)$ . Let  $f(x) = \int_{\mathbb{R}} h(x, y) dy$ . The hypotheses on h easily imply that f is a nontrivial, nonnegative  $L^1$ -function on  $\mathbb{R}$  which is supported in  $\mathbb{R}^+$ . Now if  $\hat{f}$  is the one-dimensional Fourier transform of f, then  $\hat{f}$  can be extended to a bounded function g in the region  $S = \{z \in \mathbb{C}; \text{Im } z \leq 0\}$ . g will be analytic in  $S_0 = \{z \in \mathbb{C}; \text{Im } z < 0\}$  and continuous in S. Thus  $\hat{f}$  is the "boundary-value" of a bounded analytic function in  $S_0$  and consequently  $\hat{f}$  cannot vanish identically on any nonempty open subset of  $\mathbb{R}$ , i.e. Supp  $\hat{f} = \mathbb{R}$ . Now observe that if  $\hat{h}$  is the (two dimensional) Fourier transform of h, then

$$\hat{h}(\lambda,0) = \int_{\mathbf{R}^2} h(x, y) e^{-i\lambda x} dx dy = \hat{f}(\lambda).$$

Thus Supp  $\hat{h} \supset \mathbf{R} \times \{0\}$  because Supp  $\hat{f} = \mathbf{R}$ .

Now we drop the assumption that  $h \in L^1(\mathbb{R}^2)$ . To prove the proposition let us assume  $\hat{h}$  vanishes in a neighborhood U (in  $\mathbb{R}^2$ ) of a point  $(\lambda_0, 0) \in \mathbb{R} \times \{0\}$ . Choose  $\epsilon$  sufficiently small such that the open ball of radius  $2\epsilon$  with centre at  $(\lambda_0, 0)$ is contained in U. Let  $0 \neq h_1$  be a nonnegative function in  $L^1(\mathbb{R}^2)$  such that  $\hat{h}_1$  is a  $C^{\infty}$ -function and  $\operatorname{Supp} \hat{h}_1$  is contained in the ball of radius  $\epsilon$  around 0. (It is always possible to do this.) Then  $\operatorname{Supp}(hh_1) = \operatorname{Supp}(\hat{h} * \hat{h}_1) \subset \operatorname{Supp} \hat{h} + \operatorname{Supp} \hat{h}_1$ . So if  $U' = \{(x, y) \in \mathbb{R}^2; \sqrt{(x - \lambda_0)^2 + y^2} < \epsilon\}$ , then  $\operatorname{Supp}(hh_1) \cap U' = \emptyset$ . However  $hh_1$  is a nonnegative  $L^1$ -function with  $\operatorname{Supp} hh_1 \subseteq H$  and by the first part of our proof  $hh_1$  must be zero almost everywhere on  $\mathbb{R}^2$ . Since  $\hat{h}_1$  is a  $C^{\infty}$ -function of compact support,  $h_1$  is the restriction of an entire function to  $\mathbb{R}^2$  and hence  $h_1(x) \neq 0$  a.e. on  $\mathbb{R}^2$ . Thus h is zero a.e. which gives us a contradiction and the proof of our proposition is complete.

## ALLADI SITARAM

Proposition 3.1 and the Proposition in §2 easily imply the following generalization of the Cramér-Wold theorem.

THEOREM 3.2. Let E be a Borel subset of H such that  $\lambda(E) > 0$ . Let  $\mu, v \in C$  such that  $\mu(\sigma(E)) = v(\sigma(E))$  for all rigid motions  $\sigma$  of  $\mathbb{R}^2$ . Then  $\mu = v$ .

**PROOF.** Let *l* be any line through (0,0) in  $\mathbb{R}^2$ . We will prove  $\hat{\mu} = \hat{v}$  on *l*. By Proposition 3.1, Supp  $\hat{1}_E \supseteq \mathbb{R} \times \{0\}$ . This implies that there exists a rotation *T* of  $\mathbb{R}^2$ such that Supp  $\hat{1}_{TE} \supseteq l$ . Now  $\mu(\sigma(E)) = v(\sigma(E))$  for all rigid motions  $\sigma$ , implies that  $\check{\mu} * 1_{TE} = \check{v} * 1_{TE}$  (where  $\check{\mu}(A) = \mu(-A)$ ), for every rotation *T* of  $\mathbb{R}^2$ . Thus by the Proposition in §2 it follows that  $(\check{\mu}) = (\check{v})$  on *l*. Since *l* is arbitrary this implies  $(\check{\mu}) = (\check{v})$ , i.e.  $\check{\mu} = \check{v}$ , i.e.  $\mu = v$ , and the proof of our theorem is complete.

REMARK. The technique used in this paper is essentially that of [1]—this paper could be considered a continuation of [1].

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716