

FLEXURAL ANALYSIS OF LAMINATED COMPOSITES USING REFINED HIGHER-ORDER C^0 PLATE BENDING ELEMENTS

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A finite element formulation for flexure of a symmetrically laminated plate based on a higher-order displacement model and a three-dimensional state of stress and strain is presented here. The present higher-order theory incorporates linear variation of transverse normal strains and parabolic variation of transverse shear strains through the plate thickness, and as a result it does not require shear correction coefficients. A nine-noded Lagrangian parabolic isoparametric plate bending element is described. The applications of the element to bending of laminated plates with various loading, boundary conditions, and lamination types are discussed. The numerical evaluations also include the convergence study of the element used. The present solutions for deflections and stresses are compared with those obtained using the three-dimensional elasticity theory, closed-form solutions with another high-order shear deformation theory, and the Mindlin's theory. In addition, numerical results for a number of new problems, not available in the literature, are presented for future reference.

1. Introduction

Multilayered composites are important structural materials in weight sensitive aerospace applications, where high strength-to-weight and stiffness-to-weight ratios are desired. Such composites, idealized as orthotropic lamina, are bonded together to form a laminate and are used as structural components. The finite element formulation provides a convenient method of solution for such laminated composites having complex geometry and arbitrary loading as well as support conditions.

Analysis of such a laminate in the past has been based on one of the following two types of plate theories:

- The classical lamination theory based on Kirchhoff hypothesis.
- First-order shear deformation theories.

In both theories it is assumed that the laminate is in a state of plane stress. The classical lamination theory [1, 2], which is an extension of the classical thin plate theory [3, 4] to laminated plates, neglects the effects due to transverse shears and normal strain in the thickness direction. It was soon realised that these effects are more significant for laminated composite plates than for isotropic plates due to high ratio of in-plane modulus to transverse shear modulus. Further, it was also observed that the classical thin plate theory based on the so-called Kirchhoff hypothesis is computationally inefficient (C^1 continuous) from the point of view of simple finite element formulations [5, 6]. The errors in such a theory naturally increase as the plate aspect ratio ($a/h < 10$) decreases. For instance, in plates with aspect ratio less than

ten and high degree of orthotropy, Ashton and Whitney [7] have reported enormous discrepancy in the results of the classical thin plate theory.

The shear deformation theories which include transverse shear deformation can be classified on the basis of the assumed fields as (i) stress-based theories and (ii) displacement-based theories. Reissner [8] and Mindlin [9] are the two pioneers to provide first-order shear deformable theories based on the assumed stresses and displacements variation through the thickness of the plate, respectively. Medwadowski [10] has extended Reissner's theory to orthotropic plates. Yang, Norris and Stavsky [11], on the other hand, have extended Mindlin's theory to heterogeneous plates.

The foregoing theories provide a first-order basis for the consideration of the transverse shear deformations effect on the behaviour of isotropic, orthotropic, and heterogeneous plates and these also yield a C^0 continuous finite element formulation for the numerical analysis but have certain limitations:

- The transverse shearing strains/stresses are assumed constant through the plate thickness and a fictitious shear correction coefficient is introduced.
- The nonzero transverse shear stresses on the bounding planes of the plate are contradictory to the basic requirements for the equilibrium.
- The classical contradiction whereby the plates are assumed to be in a state of plane stress/strain remains unresolved.

Reissner [12] and Lo, Christensen and Wu [13, 14] have presented a theory for plates based on assumed higher-order displacement field. Kant [15] has derived an isotropic version of the complete governing equation of such a theory based on the minimum potential energy principle and has also compared it with Mindlin theory through extensive numerical studies. A C^0 finite element formulation of this higher-order theory is presented by Kant, Owen and Zienkiewicz [16]. In this theory, the in-plane and the transverse displacements are expanded in the powers of the thickness coordinate (z) by Taylor series and the truncations are effected at the third and the second degrees, respectively. The theory thus incorporates:

- Quadratic variation of the transverse shearing strains (γ_{xz} and γ_{yz}) through the plate thickness, avoiding the introduction of a shear correction factor.
- Linear variation of the transverse normal strain (ϵ_z) through the plate thickness
- Consideration of the complete three-dimensional Hooke's law.

Pandya and Kant [17] have extended this theory for generally orthotropic plates. The present work is a further development of this theory for flexure of symmetrically laminated anisotropic composite plates.

Recently, Bert [18] has presented an evaluation of various plate theories developed for laminated composites. Phan and Reddy [19] have presented a finite element formulation of a plate theory based on an assumed displacement field of Levinson [20] and Murthy [21] in which in-plane displacements are expanded as cubic functions of the thickness coordinate while the transverse deflection is kept only a function of x and y as assumed in the classical shear deformation theories. Hence, implicit in this development is the use of only a partial constitutive relation which ignores the contributions and effects of transverse normal stress (σ_z)/strain (ϵ_z). The higher-order functions used in the definition of the in-plane displacements are eliminated and expressed in terms of the usual physical lower-order displacement functions of the classical shear deformable theories by conditioning that the transverse shear stresses are zero on the bounding planes of the plates. The resulting formulation is seen to

contain second-order derivatives of the transverse deflection (w) in the energy expression and consequently the displacement-based finite element formulation requires the use of computationally inefficient C^1 continuous shape functions. Further, for laminated composite plates, the evaluation of transverse shear stresses from the constitutive relations is not justified technically as it violates the continuity of transverse shear stresses at the interfaces. In addition, it is noted that for the laminated composite plates, the feasible and accurate prediction of transverse shear stresses are cumbersome [22] and can only be obtained from the stress equilibrium equations which satisfy both the requirements of zero transverse shear stresses on the bounding planes of the plate as well as transverse shear stress continuity at the interfaces.

An extremely important aspect in the design and manufacture of the fibre-reinforced laminates is the prediction of its failure mode(s) under the given set of load conditions. The delamination mode of the failure is now recognized as the most critical one [23]. This type of failure mode is due to interlaminar stresses τ_{xz} , τ_{yz} , and also σ_z , which is not considered by Reddy [19], Levinson [20], and Murthy [21]. We believe the present formulation has the potential to predict all the six components of stresses and displacement components accurately. In order to demonstrate the accuracy and efficiency of the present finite element technique, solutions of problems for which analytical solutions [22, 24] are available are selected so that a comparison between the analytical and numerical solutions could be made. In addition, numerical results are presented for various other boundary conditions and loading cases, some of which may serve as bench marks for future investigators.

2. A higher-order theory for composite laminates

The development of the present theory starts with the assumption of the displacement field in the following form:

$$\begin{aligned} U(x, y, z) &= z\theta_x(x, y) + z^3\theta_x^*(x, y), \\ V(x, y, z) &= z\theta_y(x, y) + z^3\theta_y^*(x, y), \\ W(x, y, z) &= w(x, y) + z^2w^*(x, y), \end{aligned} \quad (1)$$

in which the various terms have the usual meaning except the terms θ_x^* , θ_y^* , and w^* which are the corresponding higher-order terms in the Taylor-series expansion and are defined at the reference plane in the present theory [15, 16].

By substitution of these relations into the strain-displacement equations of the classical theory of elasticity [1] the following relationships are obtained:

$$\begin{aligned} \epsilon_x &= zK_x + z^3K_x^*, & \epsilon_y &= zK_y + z^3K_y^*, & \epsilon_z &= zK_z, \\ \gamma_{xy} &= zK_{xy} + z^3K_{xy}^*, & \gamma_{yz} &= \varphi_y + z^2\varphi_y^*, & \gamma_{xz} &= \varphi_x + z^2\varphi_x^*, \end{aligned} \quad (2)$$

in which

$$[K_x, K_y, K_{xy}]^t = [\partial\theta_x/\partial x, \partial\theta_y/\partial y, \partial\theta_x/\partial y + \partial\theta_y/\partial x]^t,$$

$$[K_x^*, K_y^*, K_{xy}^*, K_z^*]^t = [\partial\theta_x^*/\partial x, \partial\theta_y^*/\partial y, \partial\theta_x^*/\partial y + \partial\theta_y^*/\partial x, 2w^*]^t \quad (2a)$$

$$[\varphi_x, \varphi_y]^t = [\partial w/\partial x + \theta_x, \partial w/\partial y + \theta_y]^t,$$

$$[\varphi_x^*, \varphi_y^*]^t = [\partial w^*/\partial x + 3\theta_x^*, \partial w^*/\partial y + 3\theta_y^*]^t.$$

The stress-strain relationship for the l th layer (lamina) of the composite laminate has the following form:

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{yz} \\ \tau_{xz} \end{Bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} & Q_{14} & 0 & 0 \\ Q_{12} & Q_{22} & Q_{23} & Q_{24} & 0 & 0 \\ Q_{13} & Q_{23} & Q_{33} & Q_{34} & 0 & 0 \\ Q_{14} & Q_{24} & Q_{34} & Q_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & Q_{55} & Q_{56} \\ 0 & 0 & 0 & 0 & Q_{56} & Q_{66} \end{bmatrix} \begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \varepsilon_z \\ \gamma_{xy} \\ \gamma_{yz} \\ \gamma_{xz} \end{Bmatrix}. \quad (3)$$

This may be written in a compact form as

$$\sigma = \underline{Q}\varepsilon, \quad (3a)$$

where σ and ε are stress and strain vectors, respectively, with reference to plate axes (x, y, z) (see Fig. 1). The stiffness matrix \underline{Q} with reference to plate axes is obtained from the stiffness matrix \underline{C} with reference to fibre axes (1-2-3) by using the coordinate transformation matrix \underline{T} from the relation,

$$\underline{Q} = \underline{TCT}^t. \quad (4)$$

The elements of matrices \underline{C} , \underline{Q} , and \underline{T} are defined in Appendices A, B, and C, respectively.

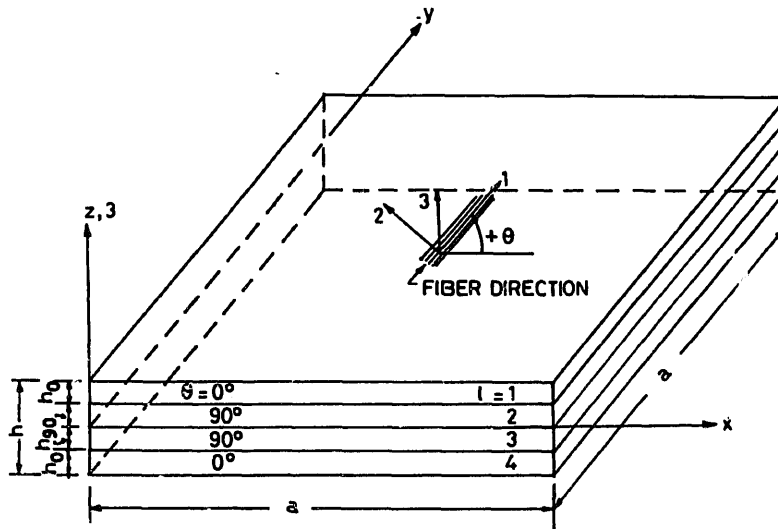


Fig. 1. Geometry of a four-layer symmetric laminate.

Integration through thickness of (3) with strain terms given by (2) gives the plate constitutive relations. The constitutive relations involving bending moments are given by

$$\mathbf{M} = \underline{\mathbf{D}}_b \mathbf{K}, \quad (5)$$

in which

$$\mathbf{M} = (M_x, M_y, M_{xy}, M_x^*, M_y^*, M_{xy}^*, M_z)^t,$$

$$\mathbf{K} = (K_x, K_y, K_{xy}, K_x^*, K_y^*, K_{xy}^*, K_z)^t,$$

$$\underline{\mathbf{D}}_b = \sum_{l=1}^n \begin{bmatrix} Q_{11}H_1 & Q_{12}H_1 & Q_{14}H_1 & Q_{11}H_2 & Q_{12}H_2 & Q_{14}H_2 & Q_{13}H_1 \\ & Q_{22}H_1 & Q_{24}H_1 & Q_{12}H_2 & Q_{22}H_2 & Q_{24}H_2 & Q_{23}H_1 \\ & & Q_{44}H_1 & Q_{14}H_2 & Q_{24}H_2 & Q_{44}H_2 & Q_{34}H_1 \\ & & & Q_{11}H_3 & Q_{12}H_3 & Q_{14}H_3 & Q_{13}H_2 \\ & & & & Q_{22}H_3 & Q_{24}H_3 & Q_{23}H_2 \\ & & & & & Q_{44}H_3 & Q_{34}H_2 \\ \text{Symmetric} & & & & & & Q_{33}H_1 \end{bmatrix}^{l\text{th layer}}, \quad (5a)$$

where

$$n = \text{No. of layers in a laminate},$$

$$H_1 = \frac{1}{3}(h_l^3 - h_{l+1}^3), \quad H_2 = \frac{1}{5}(h_l^5 - h_{l+1}^5), \quad H_3 = \frac{1}{7}(h_l^7 - h_{l+1}^7). \quad (5b)$$

The elements of the moment vector \mathbf{M} are defined as follows:

$$\begin{bmatrix} M_x & M_x^* \\ M_y & M_y^* \\ M_{xy} & M_{xy}^* \end{bmatrix} = \sum_{l=1}^n \int_{h_{l+1}}^{h_l} \begin{bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{bmatrix} [z, z^3] dz, \quad (5c)$$

$$M_z = \sum_{l=1}^n \int_{h_{l+1}}^{h_l} \sigma_z Z dz. \quad (5d)$$

The constitutive relations involving shear forces are given by

$$\mathbf{Q} = \underline{\mathbf{D}}_s \boldsymbol{\varphi}, \quad (6)$$

where

$$\mathbf{Q} = (Q_x, Q_y, Q_x^*, Q_y^*)^t, \quad \boldsymbol{\varphi} = (\varphi_x, \varphi_y, \varphi_x^*, \varphi_y^*)^t,$$

$$\underline{\mathbf{D}}_s = \sum_{l=1}^n \begin{bmatrix} Q_{66}H & Q_{56}H & Q_{66}H_1 & Q_{56}H_1 \\ & Q_{55}H & Q_{56}H_1 & Q_{55}H_1 \\ & & Q_{66}H_2 & Q_{56}H_2 \\ \text{Symmetric} & & & Q_{55}H_2 \end{bmatrix}^{l\text{th layer}}, \quad (6a)$$

in which $H = (h_l - h_{l+1})$ and H_1, H_2 are already defined. The components of the shear force vector Q are defined as follows:

$$\begin{bmatrix} Q_x & Q_x^* \\ Q_y & Q_y^* \end{bmatrix} = \sum_{l=1}^n \int_{h_{l+1}}^{h_l} \begin{bmatrix} \tau_{xz} \\ \tau_{yz} \end{bmatrix} [1, z^2] dz. \quad (6b)$$

3. Finite element discretization

We follow the standard finite element discretization procedure in which the total solution domain Ω is subdivided into 'ME' subdomains (elements) $\Omega_1, \Omega_2, \dots, \Omega_{ME}$ such that

$$\Pi(d) = \sum_{e=1}^{ME} \Pi^e(d), \quad (7)$$

where Π and Π^e are the total potential of the system and the element, respectively. We further express

$$\Pi^e(d) = U^e - W^e, \quad (8)$$

in which U^e and W^e are the internal strain energy and the external work done expressions, respectively, and d is the vector of dependent displacement variables in the problem and is defined in the present case as:

$$d = (w, \theta_x, \theta_y, w^*, \theta_x^*, \theta_y^*)^t. \quad (9)$$

In the C^0 finite element theory the continuum displacement vector within the element is discretized such that

$$d = \sum_{i=1}^{NE} N_i(x, y) d_i, \quad (10)$$

in which the term $N_i(x, y)$ is the interpolating (shape or basis) function associated with node i , d_i is the value of d corresponding to node i , and 'NE' is the number of nodes in the element. Equation (10) ensures that the approximate d is not only continuous within the element but over the entire domain since the same value of d is used for all the elements at the common nodes. Thus C^0 formulation makes the relation (7) a true one.

In the present analyses, the nine-noded quadrilateral from the Lagrangian family of two-dimensional C^0 continuous isoparametric elements with six degrees of freedom per node as per (9) is developed. With the generalized displacement vector d known at all points within the element as per (10), the generalized strain vector $\bar{\epsilon}$ at any point is expressed as follows:

$$\bar{\epsilon} = \sum_{i=1}^9 \begin{bmatrix} 0 & \frac{\partial N_i}{\partial x} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{\partial N_i}{\partial y} & 0 & 0 & 0 \\ 0 & \frac{\partial N_i}{\partial y} & \frac{\partial N_i}{\partial x} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{\partial N_i}{\partial x} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{\partial N_i}{\partial y} \\ 0 & 0 & 0 & 0 & \frac{\partial N_i}{\partial y} & \frac{\partial N_i}{\partial x} \\ 0 & 0 & 0 & 2N_i & 0 & 0 \\ \frac{\partial N_i}{\partial x} & N_i & 0 & 0 & 0 & 0 \\ \frac{\partial N_i}{\partial y} & 0 & N_i & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{\partial N_i}{\partial x} & 3N_i & 0 \\ 0 & 0 & 0 & \frac{\partial N_i}{\partial y} & 0 & 3N_i \end{bmatrix} \begin{Bmatrix} w_i \\ \theta_{xi} \\ \theta_{yi} \\ w_i^* \\ \theta_{xi}^* \\ \theta_{yi}^* \end{Bmatrix}, \quad (11a)$$

or

$$\bar{\epsilon} = \sum_{i=1}^9 \underline{B}_i d_i, \quad (11b)$$

where

$$\bar{\epsilon} = (K_x, K_y, K_{xy}, K_x^*, K_y^*, K_{xy}^*, K_z, \varphi_x, \varphi_y, \varphi_x^*, \varphi_y^*)^t. \quad (11c)$$

The elasticity matrix \underline{D} is obtained by combining (5) and (6) as follows:

$$\underline{D} = \begin{bmatrix} \underline{D}_b & | & - \\ 0 & | & \underline{D}_s \end{bmatrix}. \quad (12)$$

Upon evaluating the matrices \underline{D} and \underline{B} as given by (11) and (12), respectively, the element stiffness matrix can be readily computed using the standard relation,

$$K_{ij}^e = \int_{-1}^{+1} \int_{-1}^{+1} \underline{B}_i^t \underline{D} \underline{B}_j |J| d\xi d\eta. \quad (13)$$

The computation of element stiffness matrix is economized by explicit multiplication of the matrices \underline{B}_i , \underline{D} , and \underline{B}_j instead of carrying out the full matrix multiplication of the triple product and due to symmetry of the stiffness matrix, only the blocks \underline{K}_{ij} lying on one side of the main diagonal are formed [25].

The consistent load vector \mathbf{P} due to distributed load p can be written as:

$$\mathbf{P} = \int_{-1}^{+1} \int_{-1}^{+1} \underline{\mathbf{N}}^t p |\underline{\mathbf{J}}| d\xi d\eta. \quad (14)$$

The total potential energy Π for the present theory [16] is given by

$$\Pi = \frac{1}{2} \int_A \bar{\boldsymbol{\varepsilon}}^t \bar{\boldsymbol{\sigma}} dA - \int_A (p_z^+ + p_z^-) (w + \frac{1}{4} h^2 w^*) dA, \quad (15)$$

where p_z^+ and p_z^- are the transverse distributed loads on the positive and negative extreme z -planes, respectively, and h is the total thickness of the plate. The generalized stress component vector $\bar{\boldsymbol{\sigma}}$ is given by

$$\bar{\boldsymbol{\sigma}} = (M_x, M_y, M_{xy}, M_x^*, M_y^*, M_{xy}^*, M_z, Q_x, Q_y, Q_x^*, Q_y^*)^t. \quad (16)$$

Equation (14) for consistent load vector takes the following form suitable for numerical integration when transformed in the context of the energy expression (15) for the present theory:

$$\mathbf{P} = \sum_{a=1}^g \sum_{b=1}^g W_a W_b |\underline{\mathbf{J}}| \mathbf{N}_i \begin{Bmatrix} 1 \\ 0 \\ 0 \\ \frac{1}{4} h^2 \\ 0 \\ 0 \end{Bmatrix} (p_z^+ + p_z^-), \quad (17)$$

where W_a and W_b are weighting coefficients, g is the number of numerical quadrature points in each direction and $\underline{\mathbf{J}}$ is the standard Jacobian matrix.

The consistent load vector for a sinusoidal transverse load acting on top surface of the plate is obtained by the following substitution in (17):

$$p_z^+ = p_{mn} \sin \frac{m\pi x}{a} \sin \frac{n\pi y}{b}, \quad (18a)$$

$$p_z^- = 0, \quad (18b)$$

where a and b are the plate dimensions, x and y are the Gauss point coordinates, and m and n are the usual harmonic numbers.

4. Numerical examples

A computer program incorporating the present higher-order theory is developed for the analysis of a symmetrically laminated composite plate. All the computations on the present theory are supported by Mindlin's theory [26]. In all the numerical examples, except for the convergence study, a quarter plate is discretized with four of the nine-noded Lagrangian

quadrilateral elements. The selective integration scheme based on Gauss–Legendre product rules, namely 3×3 and 2×2 , has been employed for flexural and shear contributions, respectively, for the computation of the element stiffness matrix. Mindlin's theory computations are with a shear correction factor of $\frac{5}{6}$. For the present higher-order as well as Mindlin's theory, single values presented for transverse shear stresses represent the one obtained from equilibrium equations. To study the difference in shear stresses obtained from equilibrium equations and the constitutive relation, both the values are presented for few examples. The values given within parentheses refer to those obtained using the plate constitutive relations. The boundary conditions for different types of supports considered in the present study with the higher-order theory are as follows:

$$\text{Simply supported (SS): } w = \theta_t = w^* = \theta_t^* = 0 ; \quad (19a)$$

$$\text{Just supported (JS): } w = w^* = 0 ; \quad (19b)$$

$$\text{Clamped (CL): } w = \theta_t = \theta_n = w^* = \theta_t^* = \theta_n^* = 0 . \quad (19c)$$

Similar boundary conditions for Mindlin theory are obtained by omitting the higher-order displacement terms with asterisks.

The deflections and stresses presented are nondimensionalized with the help of the following multiplying factors for uniform pressure (p_0) or sinusoidal transverse load (p_0):

$$m_1 = \frac{100h^3 E_2}{p_0 a^4} , \quad m_2 = \frac{h^2}{p_0 a^2} , \quad m_3 = \frac{h}{p_0 a} . \quad (20)$$

Multiplying factors for central point load (P) can be obtained by replacing $p_0 a^2$ by P .

The material properties considered for all the numerical examples are:

$$\frac{E_1}{E_2} = \frac{E_1}{E_3} = 25 , \quad \frac{G_{12}}{E_2} = \frac{G_{13}}{E_3} = 0.5 , \quad \frac{G_{23}}{E_3} = 0.2 , \quad (21)$$

$$\nu_{12} = \nu_{23} = \nu_{13} = 0.25 .$$

Unless otherwise specified within the table(s) the locations (i.e. x -, y -, and z -coordinates) for critical values of displacements and stresses for the present evaluations are as follows:

$$\text{Transverse displacement (} w \text{): } (0.5a, 0.5a, 0) ; \quad (22a)$$

$$\text{In-plane normal stress (} \sigma_x \text{): } (0.4718a, 0.4718a, \frac{1}{2}h) ; \quad (22b)$$

$$\text{In-plane normal stress (} \sigma_y \text{): } (0.4718a, 0.4718a, \text{top/bottom interface}) ; \quad (22c)$$

$$\text{In-plane shear stress (} \tau_{xy} \text{): } (0.0282a, 0.0282a, \frac{1}{2}h) ; \quad (22d)$$

$$\text{Transverse shear stress (} \tau_{xz} \text{): } (0.0528a, 0.4472a, 0) ; \quad (22e)$$

$$\text{Transverse shear stress (} \tau_{yz} \text{): } (0.4472a, 0.0528a, 0) ; \quad (22f)$$

The locations for critical values of stresses for elasticity and closed-form solutions presented for comparisons are at the nearest nodal points.

The various examples considered are as follows.

EXAMPLE 4.1. A simply supported square laminated cross-ply plate ($0^\circ/90^\circ/90^\circ/0^\circ$) made up of four equally thick laminas subjected to a sinusoidal transverse load is considered for convergence study. The numerical results are presented and compared in Tables 1 and 2 for side-to-thickness ratios (a/h) of 10 and 100, respectively. The convergence of centre deflections is shown graphically in Fig. 2. It is clear from this figure that the 2×2 mesh in a quarter plate gives sufficiently accurate prediction of displacements and hence the stresses. It is advised to use refined mesh for better transverse shear stress predictions.

Table 1

Convergence of deflections and stresses in a simply supported four layer cross-ply ($0^\circ/90^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_i = \frac{1}{4}h$, $i = 1, \dots, 4$ and $a/h = 10$)

Source	Mesh size in quarter plate	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	1×1	0.72402	0.5701	0.3944	0.02705	(0.2473) 0.1862	(0.1405) 0.1159
	2×2	0.7185	0.5676	0.3948	0.02728	(0.2756) 0.2702	(0.1552) 0.1715
	3×3	0.71809	0.5635	0.3924	0.02725	(0.2803) 0.2887	(0.1578) 0.1834
	4×4	0.71801	0.5619	0.3914	0.02723	(0.2818) 0.2956	(0.1587) 0.1877
Higher-order shear deformation theory [22]	—	0.7147	0.5456	0.3888	0.02680	0.2640	0.1531
3D elasticity [24]	—	0.7370	0.5590	0.4010	0.02750	0.3010	0.1960

Table 2

Convergence of deflections and stresses in a simply supported four layer cross-ply ($0^\circ/90^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_i = \frac{1}{4}h$, $i = 1, \dots, 4$ and $a/h = 100$)

Source	Mesh size in quarter plate	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	1×1	0.43659	0.5411	0.2718	0.02148	(0.2710) 0.2045	(0.09922) 0.08562
	2×2	0.4346 (0.1114)	0.5442	0.2734	0.02154	(0.3046) 0.3024	0.1240
	3×3	0.43443	0.5418	0.2723	0.02144	(0.3109) 0.3216	(0.1136) 0.1321
	4×4	0.43439	0.5406	0.2717	0.02140	(0.3130) 0.3288	(0.1144) 0.1350
Higher-order shear deformation theory [22]	—	0.4343	0.5387	0.2708	0.02130	0.2897	0.1117
3D elasticity [24]	—	0.4347	0.5390	0.2710	0.02140	0.3390	0.1390

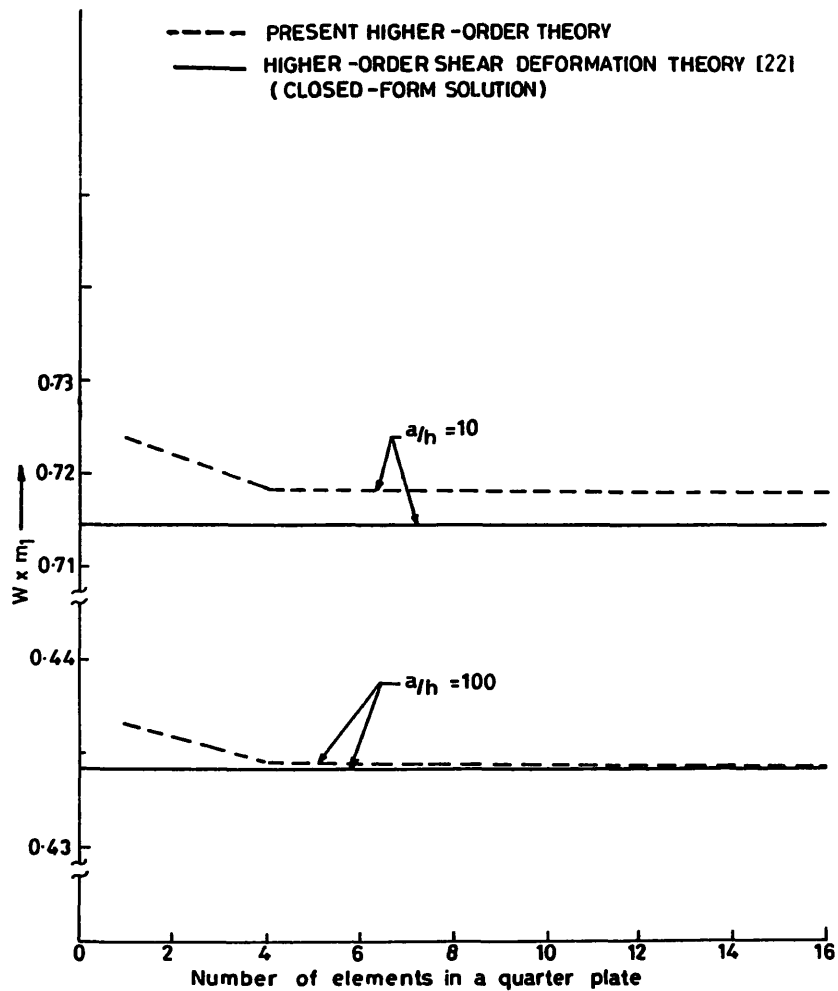


Fig. 2. Convergence of centre deflection ($w \times m_1$) with the mesh refinement for a four equal layer cross-ply ($0^\circ/90^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load.

EXAMPLE 4.2. To validate the present higher-order theory and Mindlin's theory through comparisons with three-dimensional elasticity solution and closed-form solutions of various plate theories, a simply supported square laminated cross-ply plate ($0^\circ/90^\circ/90^\circ/0^\circ$) made up of four equally thick laminas subjected to a sinusoidal transverse load is considered. The numerical results are presented in Table 3 for thin to moderately thick plates. This comparative study proves the accuracy of the present higher-order theory to predict the displacements as well as the stresses. The central transverse deflection variation with the aspect ratio (a/h) is presented in Fig. 3. The variation of in-plane normal stress in the fibre direction (σ_x) with the aspect ratios for the present higher-order and Mindlin's theory is presented in Fig. 4. Similarly, the results for a simply supported square laminated cross-ply plate ($0^\circ/90^\circ/0^\circ$) made up of three equally thick laminas subjected to uniform pressure and a central point load are presented in Tables 4 and 5, respectively. The variation of central transverse deflection and in-plane normal stress (σ_x) in fibre direction with the aspect ratios is presented in Figs. 5 and 6, respectively, for the uniform pressure loading. Similar results for the central point load are also presented in Figs. 7 and 8.

Table 3

Deflections and stresses in a simply supported four layer cross-ply ($0^\circ/90^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_i = \frac{1}{4}h$, $i = 1, \dots, 4$)

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.8744	0.7163	0.6250	0.04537	(0.2062) 0.2023	(0.2393) 0.2610
Mindlin theory		1.7054	0.4121	0.5829	0.03084	(0.1132) 0.2389	(0.1590) 0.2473
3D elasticity [24]		1.9368	0.7200	0.6630	0.04670	0.2190	0.2920
Higher-order shear deformation theory [22]		1.8937	0.6651	0.6322	0.04400	0.2064	0.2389
First-order shear deformation theory [22]		1.7100	0.4059	0.5765	0.03080	0.1398	0.1963
Present higher-order theory	10	0.7185	0.5676	0.3948	0.02728	(0.2756) 0.2702	(0.1552) 0.1715
Mindlin theory		0.6613	0.5063	0.3653	0.02415	(0.1348) 0.2819	(0.1047) 0.1600
3D elasticity		0.7370	0.5590	0.4010	0.02750	0.3010	0.1960
Higher-order shear deformation theory		0.7147	0.5456	0.3888	0.02680	0.2640	0.1531
First-order shear deformation theory		0.6628	0.4989	0.3615	0.02410	0.1667	0.1292
Present higher-order theory	100	0.4346	0.5442	0.2734	0.02154	(0.3046) 0.3014	(0.1114) 0.1240
Mindlin theory		0.4322	0.5416	0.2704	0.02135	(0.1444) 0.2921	(0.0836) 0.1231
3D elasticity		0.4347	0.5390	0.2710	0.02140	0.3390	0.1390
Higher-order shear deformation theory		0.4343	0.5387	0.2708	0.02130	0.2897	0.1117
First-order shear deformation theory		0.4337	0.5382	0.2705	0.02130	0.1780	0.1009

EXAMPLE 4.3. A simply supported seven-layer cross-ply square plate ($0^\circ/90^\circ/0^\circ/90^\circ/0^\circ/90^\circ/0^\circ$) subjected to a sinusoidal transverse load is considered first. The results obtained are compared with the three-dimensional elasticity solutions in Table 6. In addition, new results with just supported and clamped boundary conditions are presented in Tables 7 and 8, respectively. In this example, the total thickness of zero-degree layers and the ninety-degree layers is the same.

EXAMPLE 4.4. Just supported and clamped boundary conditions often occur in many practical situations. Similarly, uniform pressure and central point load are commonly occurring loading cases. Numerical results involving these boundary conditions and loading cases are not available in the literature. With a view to providing numerical results for future references a square laminated cross-ply plate ($0^\circ/90^\circ/0^\circ$) made up of three equally thick layers is considered. The results for a just supported (JS) plate under transverse sinusoidal, uniform pressure, and central point loads are presented in Tables 9, 10, and 11, respectively. Similar results for a clamped plate are presented in Tables 12, 13, and 14.

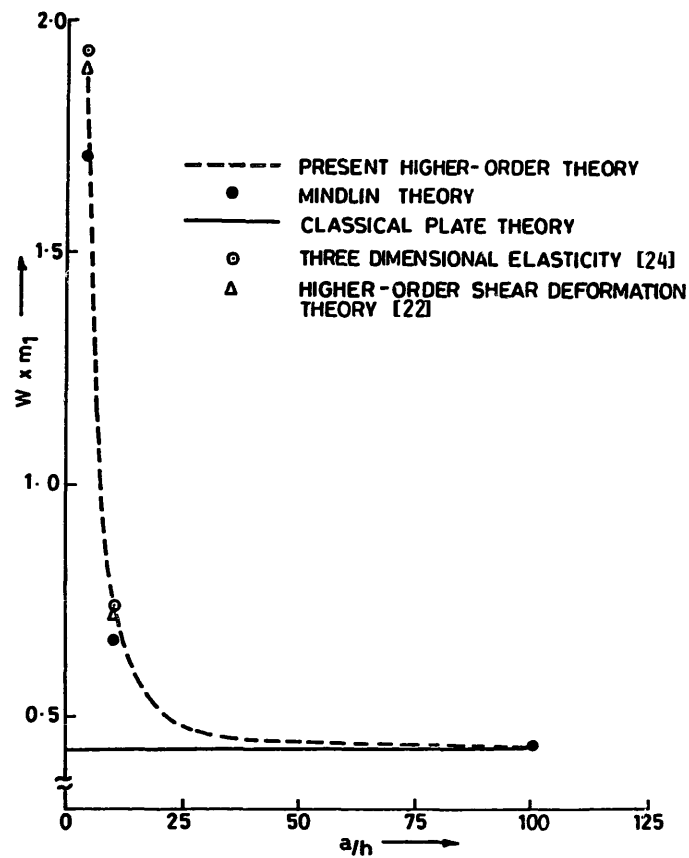


Fig. 3. Effect of plate side-to-thickness ratio (a/h) on the centre deflections ($w \times m_1$) of a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

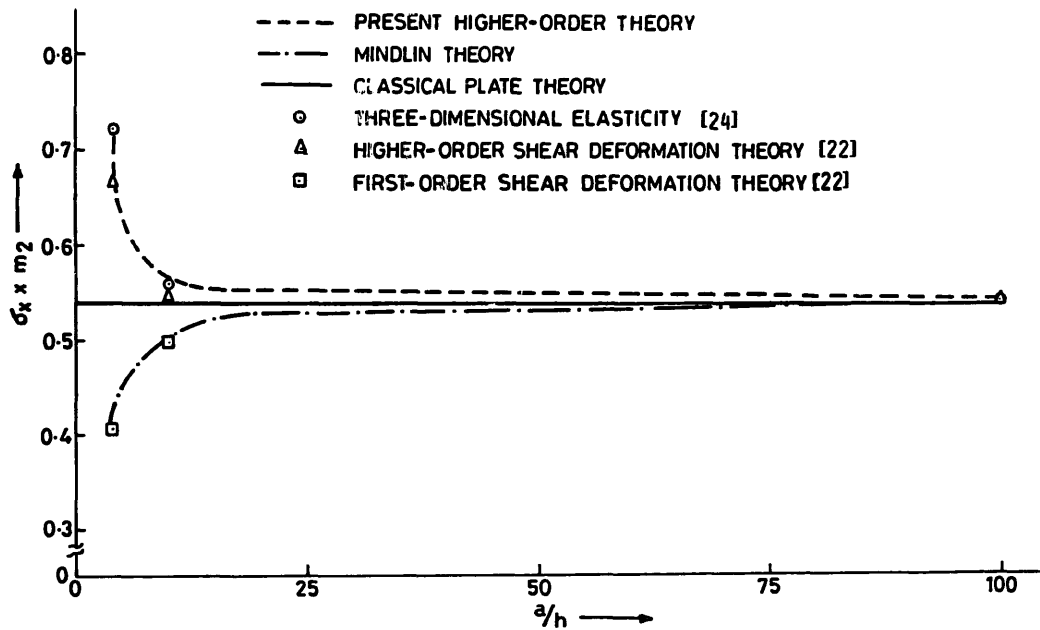


Fig. 4. Effect of plate side-to-thickness ratio (a/h) on the in-plane normal stress ($\sigma_x \times m_2$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

Table 4

Deflections and stresses in a simply supported three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under uniform pressure ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$)

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	2.8765	1.1094	0.7244	0.09463	0.4113	0.3345
Mindlin theory		2.6559	0.6650	0.6625	0.06956	0.4798	0.3030
Higher-order shear deformation theory [22]		2.9091	—	—	—	—	—
First-order shear deformation theory [22]		2.6596	—	—	—	—	—
Present higher-order theory	10	1.0968	0.8739	0.3945 ^a	0.05499	0.5202	0.1972
Mindlin theory		1.0211	0.7851	0.3844 ^a	0.04804	0.5367	0.1850
Higher-order shear deformation theory		1.0900	—	—	—	—	—
First-order shear deformation theory		1.0219	—	—	—	—	—
Present higher-order theory	100	0.6713	0.8191	0.3134 ^a	0.04137	0.5552	0.1477
Mindlin theory		0.6701	0.8190	0.2923 ^a	0.03967	0.5648	0.1480
Higher-order shear deformation theory		0.6705	—	—	—	—	—
First-order shear deformation theory		0.6697	—	—	—	—	—

^a Maximum value occurs at $(0.4718a, 0.2218a, \frac{1}{6}h)$.

Table 5

Deflections and stresses in a simply supported three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under central point load ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of shear stresses are as follows: ^b: $(0.2782a, 0.2782a, \frac{1}{2}h)$; ^c: $(0.0282a, 0.2218a, \frac{1}{2}h)$; ^d: $(0.0282a, 0.2782a, \frac{1}{2}h)$; ^e: $(0.3028a, 0.4472a, 0.0)$; ^f: $(0.4472a, 0.3028a, 0.0)$; ^g: $(0.0282a, 0.2218a, \frac{1}{2}h)$; ^h: $(0.0282a, 0.2782a, \frac{1}{2}h)$; ⁱ: $(0.3028a, 0.4472a, 0.0)$; ^j: $(0.4472a, 0.3028a, 0.0)$

Present higher-order theory	4	21.7089	6.1631	4.2306	0.1806 ^b	1.9165 ^e	2.4840 ^f
Mindlin theory		15.6905	2.8150	4.3819	0.1103	1.9815 ^e	2.4830 ^f
Present higher-order theory	10	5.3434	4.8390	3.1400	0.1015 ^b	1.7950 ^e	2.1420 ^f
Mindlin theory		4.3989	3.2290	3.1890	0.08237 ^c	2.1210 ^e	2.2150 ^f
Present higher-order theory	100	2.1593	3.6320	2.4510	0.08081 ^d	2.3550 ^e	1.8890 ^f
Mindlin theory		2.1177	3.5010	2.3840	0.07795 ^d	2.490 ^e	1.8760 ^f

Table 6

Deflections and stresses in a simply supported seven layer cross-ply ($0^\circ/90^\circ/0^\circ/90^\circ/0^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_0 = \frac{1}{8}h$, $h_{90} = \frac{1}{6}h$)

Present higher-order theory	4	1.5334	0.6275	0.5530	0.03212	0.1944	0.1995
Mindlin theory		1.5341	0.4664	0.5092	0.02228	0.2093	0.2220
3D elasticity [24]		1.7906	0.6790	0.6230	-0.03560	0.2190	0.2360
			-0.6450	-0.6100	0.03470		
Present higher-order theory	10	0.6159	0.5494	0.4482	0.02324	0.2277	0.1915
Mindlin theory		0.6114	0.5159	0.4457	0.02162	0.2292	0.1972
3D elasticity [24]		0.6594	0.5480	0.4570	0.02370	0.255	0.219
Present higher-order theory	100	0.4332	0.5439	0.4084	0.02149	0.2412	0.1831
Mindlin theory		0.4315	0.5412	0.4060	0.02136	0.2413	0.1823
3D elasticity [24]		0.4334	0.5390	0.4050	0.02130	0.2720	0.2050
Classical plate theory [24]	—	0.4331	0.5390	0.4040	0.02130	0.2720	0.2050

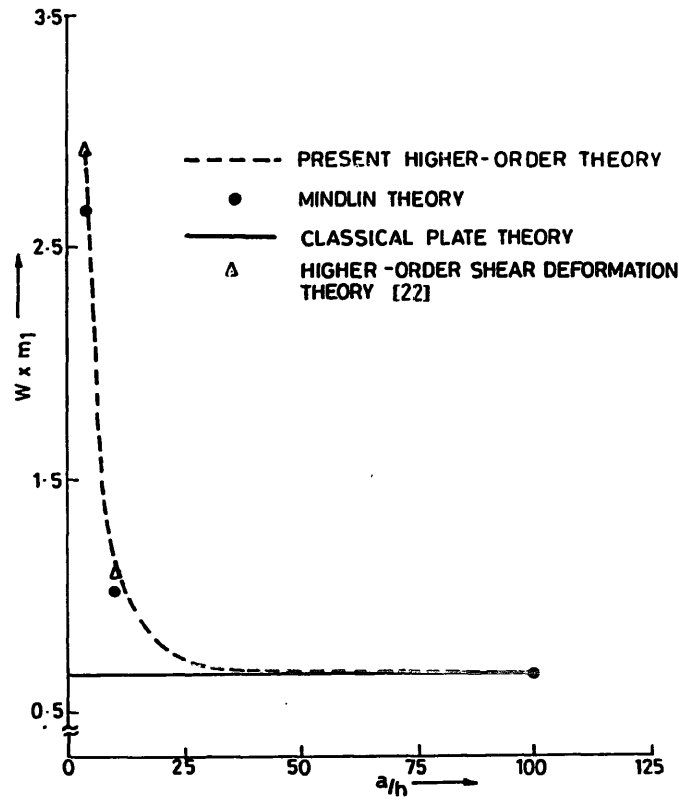


Fig. 5. Effect of plate side-to-thickness ratio (a/h) on the centre deflections ($w \times m_1$) of a simply supported $[0^\circ/90^\circ/0^\circ]$ cross-ply square laminate under uniform pressure.

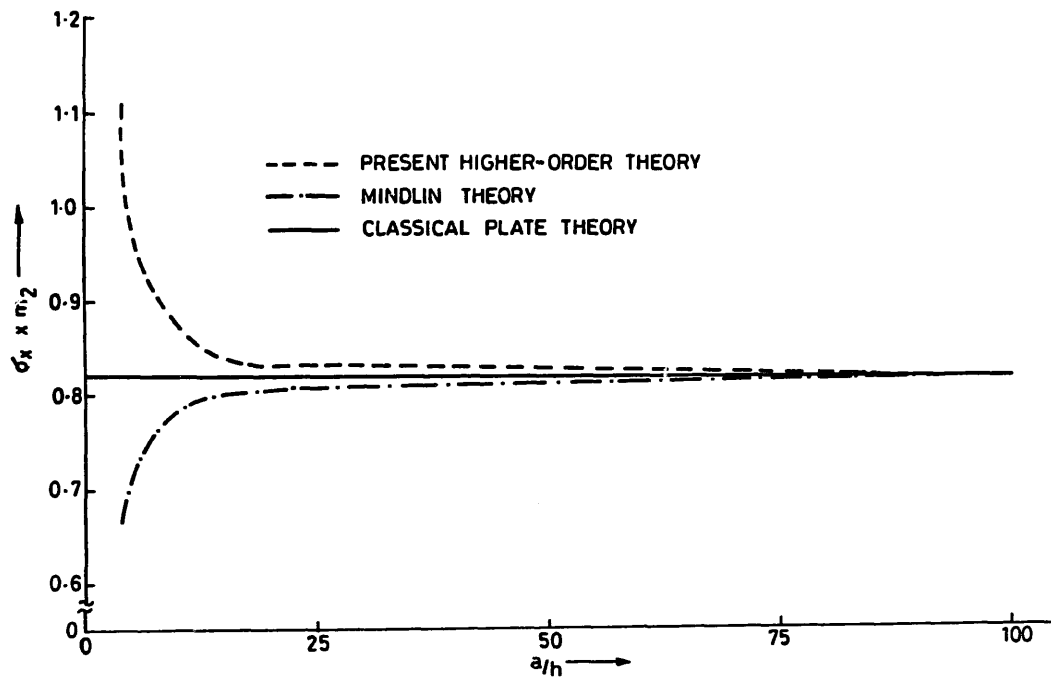


Fig. 6. Effect of plate side-to-thickness ratio (a/h) on the in-plane normal stress ($\sigma_x \times m_2$) in a simply supported $[0^\circ/90^\circ/0^\circ]$ cross-ply square laminate under uniform pressure.

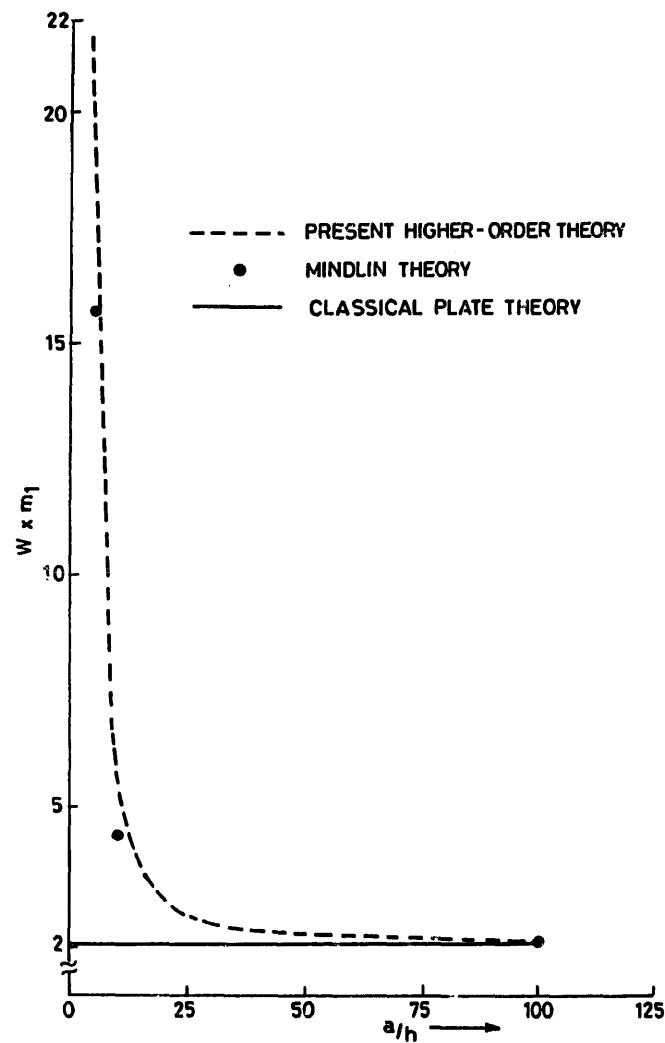


Fig. 7. Effect of plate side-to-thickness ratio (a/h) on the centre deflections ($w \times m_1$) of a simply supported $[0^\circ/90^\circ/0^\circ]$ cross-ply square laminate under central point load.

Table 7

Deflections and stresses in a just supported seven layer cross-ply ($0^\circ/90^\circ/0^\circ/90^\circ/0^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_0 = \frac{1}{8}h$, $h_{90} = \frac{1}{8}h$); locations for maximum values of shear stresses are as follows:

^b: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^c: $(0.2218a, 0.125a, \frac{1}{2}h)$; ^d: $(0.1972a, 0.4472a, 0.0)$; ^e: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.5421	0.6475	0.5677	0.02622 ^b	0.2021	0.2073
Mindlin theory		1.5495	0.4824	0.5241	0.01669 ^b	0.2266	0.2279
Present higher-order theory	10	0.6196	0.5623	0.4562	0.0209 ^b	0.2264 ^d	0.1906 ^e
Mindlin theory		0.6188	0.5255	0.4531	0.01923 ^b	0.2286 ^d	0.1949 ^e
Present higher-order theory	100	0.4354	0.5595	0.4207	0.01901 ^c	0.2343 ^d	0.1738 ^e
Mindlin theory		0.4343	0.5581	0.4192	0.01873 ^c	0.2324 ^d	0.1713 ^e

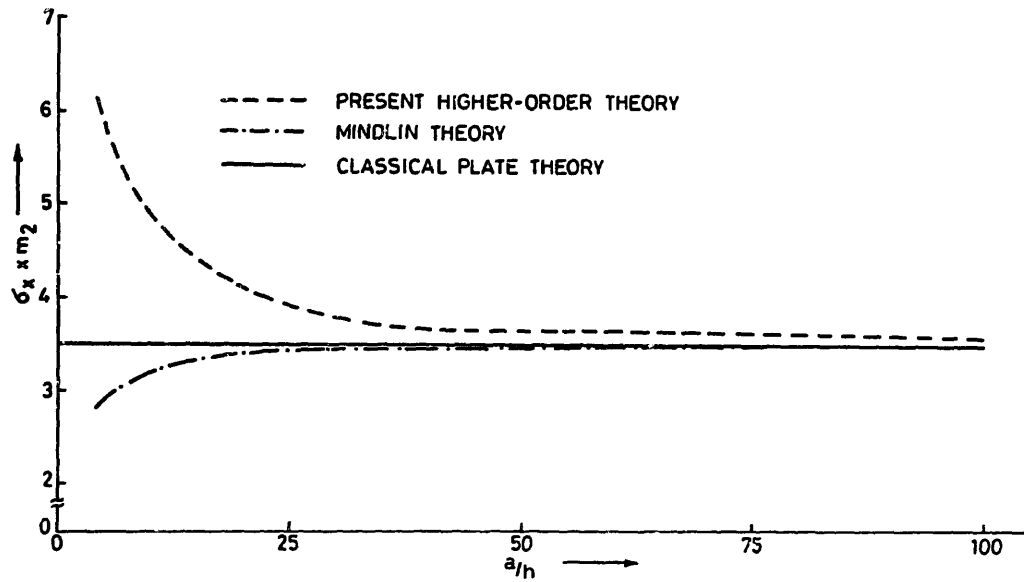


Fig. 8. Effect of plate side-to-thickness ratio (a/h) on the in-plane normal stress ($\sigma_x \times m_2$) in a simply supported $[0^\circ/90^\circ/0^\circ]$ cross-ply square laminate under central point load.

Table 8

Deflections and stresses in a clamped seven layer cross-ply ($0^\circ/90^\circ/0^\circ/90^\circ/0^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_0 = \frac{1}{8}h$, $h_{90} = \frac{1}{6}h$); locations for maximum values of stresses are as follows: ^b: $(0.0282a, 0.4718a, \frac{1}{2}h)$; ^c: $(0.4718a, 0.0282a, \frac{5}{14}h)$; ^d: $(0.125a, 0.125a, \frac{1}{2}h)$; ^e: $(0.125a, 0.2218a, \frac{1}{2}h)$; ^f: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^g: $(0.1972a, 0.4472a, \frac{3}{14}h)$; ^h: $(0.1972a, 0.4472a, 0.0)$; ⁱ: $(0.4472a, 0.0528a, \frac{3}{14}h)$; ^j: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2^b$	$\sigma_y \times m_2^c$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.1636	0.5126	0.5108	0.01099 ^d	0.1976 ^g	0.1822 ^f
Mindlin theory		1.1978	0.2488	0.3193	0.004184 ^e	0.1997	0.2407 ^s
Present higher-order theory	10	0.2893	0.3721	0.3367	0.005676 ^f	0.1923	0.2000
Mindlin theory		0.2859	0.2766	0.2942	0.004375 ^f	0.2215 ^h	0.2312 ^s
Present higher-order theory	100	0.1097	0.3379	0.2610	0.005663 ^f	0.2697	0.2122
Mindlin theory		0.1067	0.3297	0.2575	0.004622 ^f	0.2723 ^h	0.2189 ^s

Table 9

Deflections and stresses in a just supported three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of shear stresses are as follows: ^b: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^c: $(0.2218a, 0.125a, \frac{1}{2}h)$; ^d: $(0.1972a, 0.4472a, 0.0)$; ^e: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.9359	0.8113	0.5179	0.03906 ^b	0.2683	0.1900
Mindlin theory		1.8157	0.4693	0.4986	0.02710 ^b	0.3195	0.1744
Present higher-order theory	10	0.7229	0.6078	0.2754	0.02528 ^b	0.3270 ^d	0.1004 ^e
Mindlin theory		0.6773	0.5316	0.2588	0.02247 ^b	0.3386 ^d	0.09211 ^e
Present higher-order theory	100	0.4362	0.5604	0.1871	0.01918 ^c	0.3442 ^d	0.06125 ^e
Mindlin theory		0.4345	0.5590	0.1858	0.01915 ^c	0.3418 ^d	0.05914 ^e

Table 10

Deflections and stresses in a just supported three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under uniform pressure ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of stresses are as follows: ^b: $(0.4718a, 0.2218a, \frac{1}{6}h)$; ^c: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^d: $(0.2218a, 0.0282a, \frac{1}{2}h)$; ^e: $(0.1972a, 0.4472a, 0.0)$; ^f: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	2.9449	1.1681	0.7563	0.05954 ^c	0.4440	0.3420
Mindlin theory		2.7325	0.7063	0.7194 ^b	0.04084 ^c	0.5120	0.3045
Present higher-order theory	10	1.1094	0.9013	0.4296 ^b	0.03886 ^c	0.5220	0.1859 ^f
Mindlin theory		1.0375	0.8026	0.4161 ^b	0.03435 ^c	0.5392 ^e	0.1717 ^f
Present higher-order theory	100	0.6741	0.8480	0.3192 ^b	0.03269 ^d	0.5429 ^e	0.1260 ^f
Mindlin theory		0.6741	0.8519	0.3096 ^b	0.03236 ^d	0.5494 ^e	0.1179 ^f

Table 11

Deflections and stresses in a just supported three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under central point load ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values for shear stresses are as follows: ^b: $(0.2782a, 0.2782a, \frac{1}{2}h)$; ^c: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^d: $(0.2218a, 0.2782a, \frac{1}{2}h)$; ^e: $(0.125a, 0.2218a, \frac{1}{2}h)$; ^f: $(0.3028a, 0.4472a, 0.0)$; ^g: $(0.4472a, 0.3028a, 0.0)$; ^h: $(0.4472a, 0.4472a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_e^f$	$\tau_{yz} \times m_3$
Present higher-order theory	4	21.9053	6.1825	4.2856	0.1748 ^b	1.9268	2.4693 ^g
Mindlin theory		15.8403	2.9106	4.4363	0.1093 ^c	1.9773	2.4690 ^g
Present higher-order theory	10	5.4185	4.782	3.145	0.1123 ^d	1.7960	2.1210 ^g
Mindlin theory		4.4306	3.264	3.202	0.0899 ^c	2.1090	2.205 ^g
Present higher-order theory	100	2.1755	3.602	2.467	0.08714 ^d	2.3260	1.857 ^g
Mindlin theory		2.1260	3.538	2.429	0.07811 ^e	2.3080	1.849 ^g

Table 12

Deflections and stresses in a clamped three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under sinusoidal transverse load ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of stresses are as follows: ^b: $(0.0282a, 0.4718a, \frac{1}{2}h)$; ^c: $(0.4718a, 0.0282a, \frac{1}{6}h)$; ^d: $(0.125a, 0.2218a, \frac{1}{2}h)$; ^e: $(0.0282a, 0.2218a, \frac{1}{2}h)$; ^f: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^g: $(0.2218a, 0.125a, \frac{1}{2}h)$; ^h: $(0.1972a, 0.4472a, \frac{1}{6}h)$; ⁱ: $(0.0528a, 0.4472a, \frac{1}{2}h)$; ^j: $(0.1972a, 0.4472a, 0.0)$; ^k: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2^b$	$\sigma_y \times m_2^c$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.3146	0.6900	0.3754	0.01649 ^d	0.1497 ^h	0.2379
Mindlin theory		1.3376	0.2113	0.4735	0.01151 ^e	0.2660	0.2853 ⁱ
Present higher-order theory	10	0.3752	0.4909	0.2932	0.00918 ^f	0.2622 ^f	0.1877
Mindlin theory		0.3452	0.2784	0.2859	0.00704 ^d	0.3325	0.1833 ⁱ
Present higher-order theory	100	0.1081	0.3292	0.1352	0.00572 ^f	0.3815	0.1007
Mindlin theory		0.1054	0.3162	0.1390	0.00478 ^g	0.3760 ^g	0.1123 ⁱ

Table 13

Deflections and stresses in a clamped three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under uniform pressure ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of stresses are as follows: ^b: $(0.0282a, 0.4718a, \frac{1}{2}h)$; ^c: $(0.4718a, 0.0282a, \frac{1}{6}h)$; ^d: $(0.0282a, 0.2218a, \frac{1}{2}h)$; ^e: $(0.125a, 0.125a, \frac{1}{2}h)$; ^f: $(0.2218a, 0.2218a, \frac{1}{2}h)$; ^g: $(0.2218a, 0.125a, \frac{1}{2}h)$; ^h: $(0.0528a, 0.4472a, \frac{1}{6}h)$; ⁱ: $(0.1972a, 0.4472a, 0.0)$; ^s: $(0.4472a, 0.1972a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2^b$	$\sigma_y \times m_2^c$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	4	1.8891	1.0306	0.5593	0.02523 ^e	0.2374 ^g	0.4013
Mindlin theory		1.9203	0.3106	0.7175	0.01765 ^d	0.4150	0.4835 ^s
Present higher-order theory	10	0.5247	0.7282	0.4596	0.01330 ^e	0.3932 ^g	0.3416
Mindlin theory		0.4829	0.3996	0.4600	0.00992 ^e	0.5031	0.3431 ^s
Present higher-order theory	100	0.1421	0.4537	0.2498	0.00799 ^f	0.5516	0.2282
Mindlin theory		0.1388	0.4365	0.2548	0.00801 ^g	0.5441 ^r	0.2413 ^s

Table 14

Deflections and stresses in a clamped three layer cross-ply ($0^\circ/90^\circ/0^\circ$) square laminate under central point load ($h_i = \frac{1}{3}h$, $i = 1, \dots, 3$); locations for maximum values of shear stresses are as follows: ^b: $(0.4718a, 0.375a, \frac{1}{2}h)$; ^c: $(0.2782a, 0.375a, \frac{1}{2}h)$; ^d: $(0.375a, 0.375a, \frac{1}{2}h)$; ^e: $(0.3028a, 0.4472a, 0.0)$; ^f: $(0.4472a, 0.3028a, 0.0)$

Source	a/h	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3^e$	$\tau_{yz} \times m_3^f$
Present higher-order theory	4	19.5659	4.7988	3.4450	0.1628 ^b	1.8290	2.5800
Mindlin theory		14.1203	1.6288	3.8025	0.08356 ^c	1.9338	2.5950
Present higher-order theory	10	4.0740	3.5990	2.7470	0.09399 ^d	1.8040	2.1340
Mindlin theory		3.1840	1.9480	2.7830	0.06656 ^c	2.1550	2.1750
Present higher-order theory	100	0.8478	2.4280	1.7220	0.05089 ^e	2.5030	1.6370
Mindlin theory		0.8186	2.2980	1.7100	0.05495 ^e	2.4370	1.6800

Table 15

Effect of bidirectional layer thickness ratios (h_0/h_{90}) on deflection and stresses in a simply supported square laminate ($0^\circ/90^\circ/90^\circ/0^\circ$) under sinusoidal transverse load ($a/h = 10$)

Source	$\frac{h_0}{h_{90}}$	$w \times m_1$	$\sigma_x \times m_2$	$\sigma_y \times m_2$	$\tau_{xy} \times m_2$	$\tau_{xz} \times m_3$	$\tau_{yz} \times m_3$
Present higher-order theory	$\frac{1}{4}$	0.6220	0.5251	0.4885	0.02284	0.1498	0.2758
	$\frac{2}{3}$	0.6940	0.5427	0.4415	0.02588	0.2314	0.2108
	1	0.7185	0.5676	0.3948	0.02728	0.2702	0.1715
	$\frac{3}{2}$	0.7232	0.5859	0.3271	0.02799	0.3050	0.1303
	2	0.7157	0.5917	0.2735	0.02803	0.3248	0.1048
	4	0.6850	0.5902	0.1587	0.02735	0.3542	0.06527
3D elasticity [24]	1	0.7370	0.5590	0.4010	0.02750	0.3010	0.1960
	2	—	0.5900	0.2880	0.02890	0.3570	0.1228
Higher-order shear deformation theory [22]	1	0.7125	0.5684	—	—	—	0.1033
	2	0.7147	0.5456	0.3888	0.02680	0.2640	0.1531

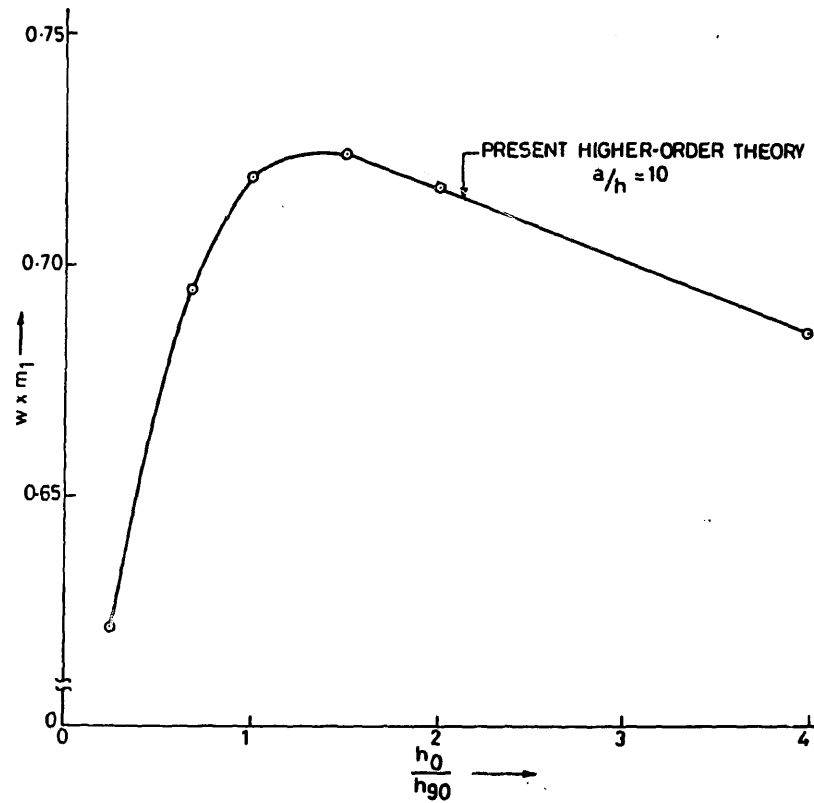


Fig. 9. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the centre deflections ($w \times m_1$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

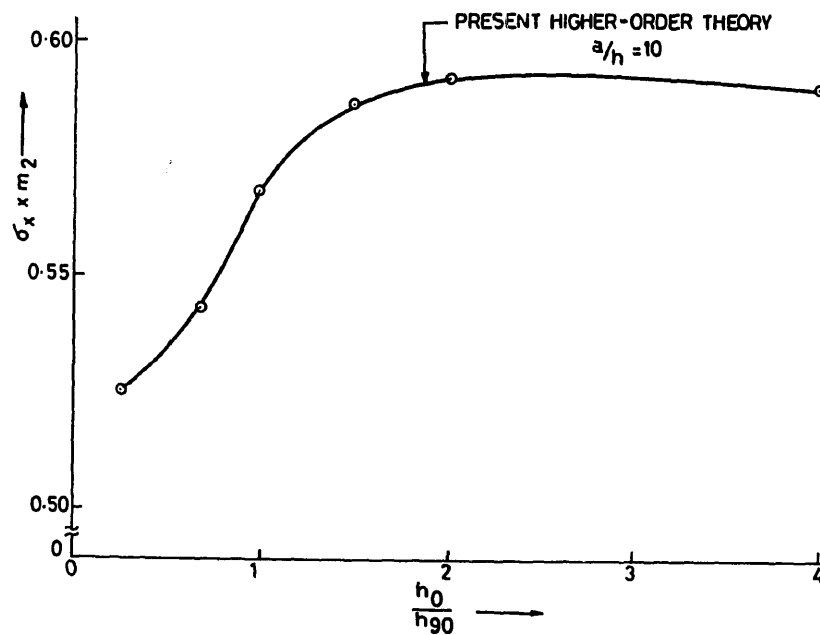


Fig. 10. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the in-plane normal stress ($\sigma_x \times m_2$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

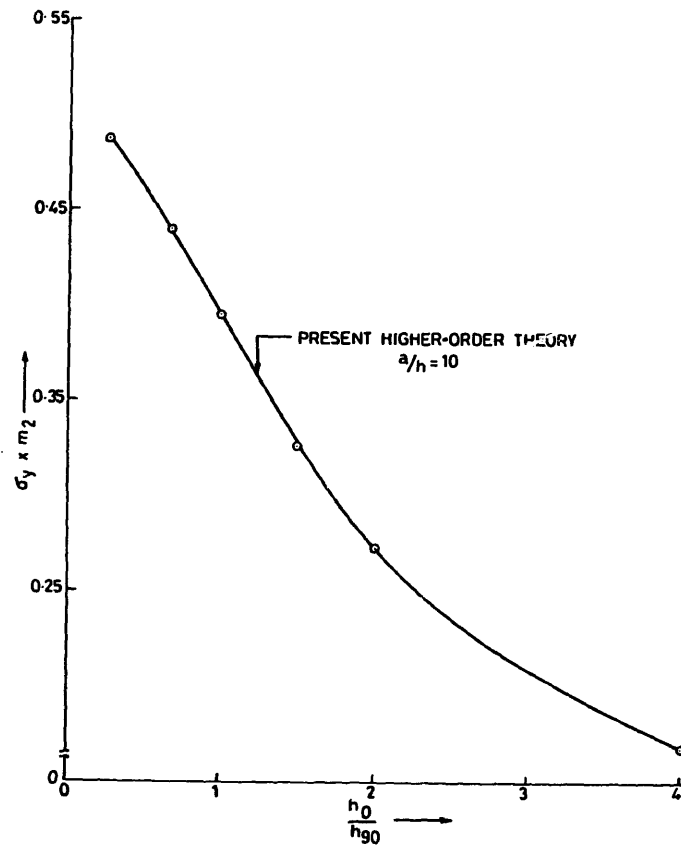


Fig. 11. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the in-plane normal stress ($\sigma_y \times m_2$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

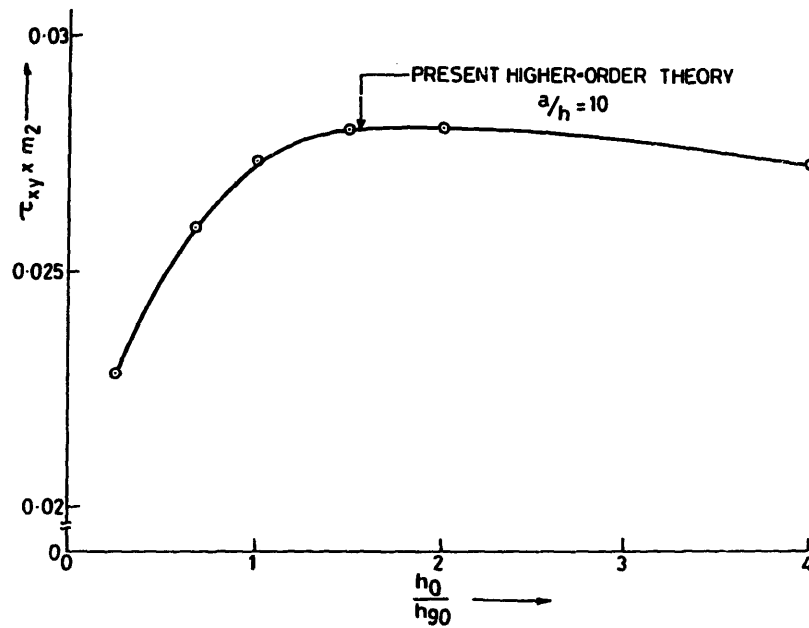


Fig. 12. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the in-plane shear stress ($\tau_{xy} \times m_2$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

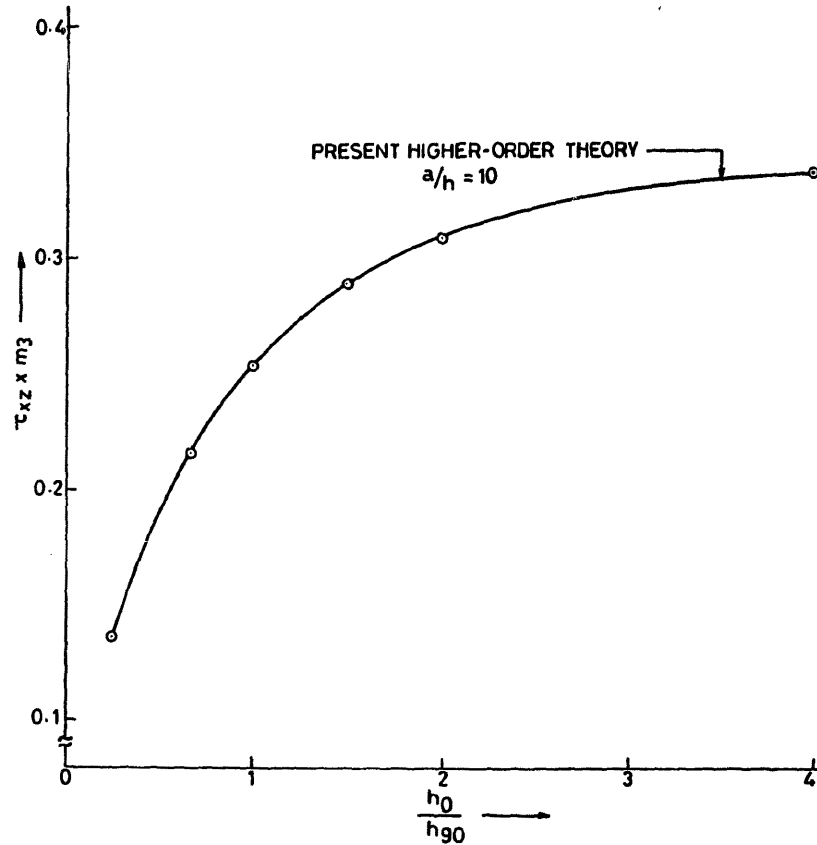


Fig. 13. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the transverse shear stress ($\tau_{xz} \times m_3$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

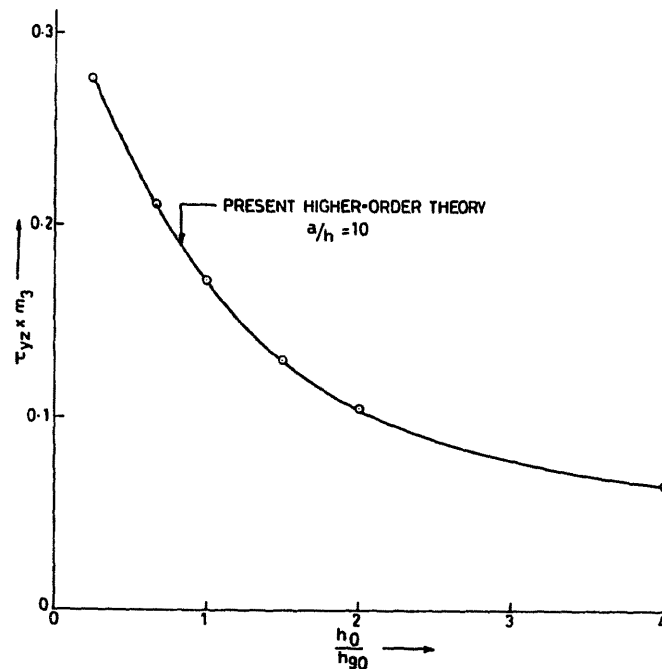


Fig. 14. Effect of bidirectional layer thickness ratio (h_0/h_{90}) on the transverse shear stress ($\tau_{yz} \times m_3$) in a simply supported $[0^\circ/90^\circ/90^\circ/0^\circ]$ cross-ply square laminate under sinusoidal transverse load.

EXAMPLE 4.5. This example is selected to bring-out the effect of bidirectional layer thickness ratios (h_0/h_{90}) on the response of a simply supported four-layer cross-ply ($0^\circ/90^\circ/90^\circ/0^\circ$) square plate under sinusoidal transverse load. The numerical results are presented in Table 15 for a plate with aspect ratio of 10. The variations of centre deflection (w), in-plane normal and shear stresses ($\sigma_x, \sigma_y, \tau_{xy}$), and transverse shear stresses (τ_{xz}, τ_{yz}) with the bidirectional layer thickness ratios are presented in Figs. 9–14, respectively.

5. Conclusions

A refined higher-order theory and Mindlin's theory are used for flexural analysis of symmetrically laminated square composite plates. A C^0 continuous finite element model of the present higher-order theory is developed and validated by comparisons with the available three-dimensional elasticity and the closed-form plate solutions. It is reasonably clear from the convergence study that a two by two mesh with 9-noded Lagrangian quadrilaterals in a quarter plate gives sufficiently accurate predictions of displacement and stresses for all practical purposes. Numerical results are presented for various commonly used boundary conditions and loading cases, some of which should serve as benchmarks for future investigators. The result of Example 4.5 may be of importance to the designers in the field of laminated composite constructions. The effects of neglecting shear deformation (as in classical lamination theory) and considering constant shear deformation (as in classical first-order shear deformation Mindlin–Reissner theories) on the response of laminated composite plates are investigated for thin to moderately thick plates. In contrast to the classical shear deformation theories, the present higher-order theory does not require shear correction coefficient due to more realistic representation of the cross-sectional deformation. In addition, the present theory includes the effect of direct normal stress in the thickness direction (σ_z) which is, though negligible, very important to study the delamination mode of failure in laminated composites. The basic foundations of this theory for the laminated anisotropic composite plates, the resulting C^0 finite element formulation, and most of the numerical results are being presented for the first time.

Appendix A. Elements of matrix [C]

$$\begin{aligned} C_{11} &= \frac{E_1(1 - \nu_{32}\nu_{23})}{A}, & C_{12} &= \frac{E_2(\nu_{12} + \nu_{13}\nu_{32})}{A} = C_{21}, \\ C_{13} &= \frac{E_3(\nu_{13} + \nu_{12}\nu_{23})}{A} = C_{31}, & C_{22} &= \frac{E_2(1 - \nu_{31}\nu_{13})}{A}, \\ C_{23} &= \frac{E_3(\nu_{23} + \nu_{13}\nu_{21})}{A} = C_{32}, & C_{33} &= \frac{E_3(1 - \nu_{12}\nu_{21})}{A}, \\ C_{44} &= G_{12}, C_{55} = G_{23}, C_{66} = G_{13}, \end{aligned}$$

where

$$A = (1 - \nu_{23}\nu_{32} - \nu_{12}\nu_{21} - \nu_{13}\nu_{31} - \nu_{12}\nu_{23}\nu_{31} - \nu_{13}\nu_{32}\nu_{21}),$$

$$\nu_{21} = \frac{E_2}{E_1} \nu_{12}, \quad \nu_{32} = \frac{E_3}{E_2} \nu_{23}, \quad \nu_{31} = \frac{E_3}{E_1} \nu_{13}.$$

Appendix B. Elements of matrix $[Q]$

$$\begin{aligned} Q_{11} &= C_{11}C^4 + 2(C_{12} + 2C_{44})C^2S^2 + C_{22}S^4, \\ Q_{12} &= (C_{11} + C_{22} - 4C_{44})C^2S^2 + C_{12}(S^4 + C^4) = Q_{21}, \\ Q_{13} &= C_{13}C^2 + C_{23}S^2 = Q_{31}, \\ Q_{14} &= (C_{12} - C_{11} + 2C_{44})C^3S - (C_{21} - C_{22} + 2C_{44})S^3C = Q_{41}, \\ Q_{15} &= Q_{16} = 0 = Q_{51} = Q_{61}, \\ Q_{22} &= C_{11}S^4 + 2(C_{12} + 2C_{44})S^2C^2 + C_{22}C^4, \\ Q_{23} &= C_{13}S^2 + C_{23}C^2 = Q_{32}, \\ Q_{24} &= (C_{12} - C_{11} + 2C_{44})S^3C - (C_{12} - C_{22} + 2C_{44})SC^3 = Q_{42}, \\ Q_{25} &= Q_{26} = 0 = Q_{52} = Q_{62}, \\ Q_{33} &= C_{33}, \\ Q_{34} &= (C_{32} - C_{31})SC = Q_{43}, \\ Q_{35} &= Q_{36} = 0 = Q_{53} = Q_{63}, \\ Q_{44} &= (C_{11} + C_{22} - 2C_{12} - 2C_{44})S^2C^2 + C_{44}(C^4 + S^4), \\ Q_{45} &= Q_{46} = 0 = Q_{54} = Q_{64}, \\ Q_{55} &= C_{55}C^2 + C_{66}S^2, \\ Q_{56} &= (C_{55} - C_{66})CS = Q_{65}, \\ Q_{66} &= C_{55}S^2 + C_{66}C^2. \end{aligned}$$

Appendix C

The stresses/strains expressed in the fibre and the plate axes are related by the following relation:

$$\sigma_x = \underline{T}\sigma_1, \quad \varepsilon_x = \underline{T}\varepsilon_1,$$

in which

$$\sigma_x = (\sigma_x, \sigma_y, \sigma_z, \tau_{xy}, \tau_{yz}, \tau_{xz})^t,$$

$$\sigma_1 = (\sigma_1, \sigma_2, \sigma_3, \tau_{12}, \tau_{23}, \tau_{13})^t,$$

$$\varepsilon_x = (\varepsilon_x, \varepsilon_y, \varepsilon_z, \gamma_{xy}, \gamma_{yz}, \gamma_{xz})^t,$$

$$\varepsilon_1 = (\varepsilon_1, \varepsilon_2, \varepsilon_3, \gamma_{12}, \gamma_{23}, \gamma_{13})^t,$$

and

$$\underline{T} = \begin{bmatrix} C^2 & S^2 & 0 & 2SC & 0 & 0 \\ S^2 & C^2 & 0 & -2SC & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -SC & SC & 0 & C^2 - S^2 & 0 & 0 \\ 0 & 0 & 0 & 0 & C & -S \\ 0 & 0 & 0 & 0 & S & C \end{bmatrix},$$

where $C = \cos \theta$, $S = \sin \theta$, and θ = fibre orientation with respect to X -axis (anticlockwise positive).

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